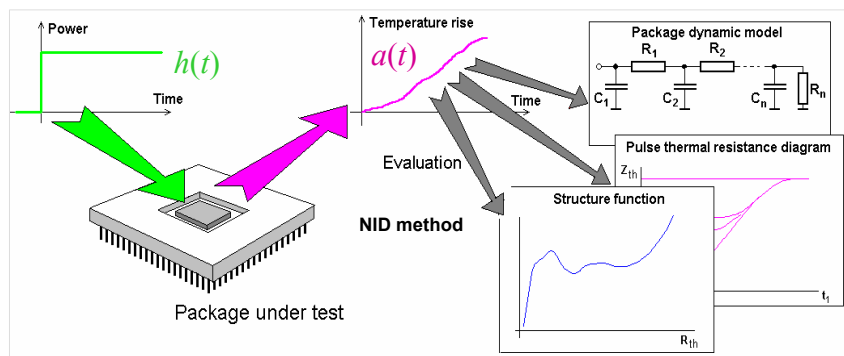


Gallop in the linear theory

- Discussed many times before
- Skip it for now, but I will upload to the server for reference

1

Thermal transient testing



The measured $a(t)$ response function is **characteristic** to the package.

The features of the *chip + package + environment* structure can be extracted from it.

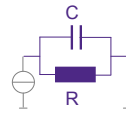
2

Step-response functions

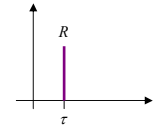
The form of the step-response function

- for a **single** RC stage:

$$a(t) = R \cdot [1 - \exp(-t/\tau)]$$



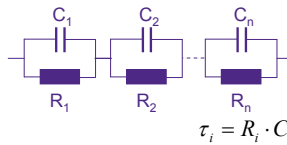
$$\tau = R \cdot C$$



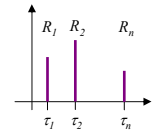
characteristic values: R magnitude and τ time-constant

- for a **chain** of n RC stages:

$$a(t) = \sum_{i=1}^n R_i \cdot [1 - \exp(-t/\tau_i)]$$



$$\tau_i = R_i \cdot C_i$$



characteristic values: set of R_i magnitudes and τ_i time-constants

If we know the R_i and τ_i values, we know the system.

3

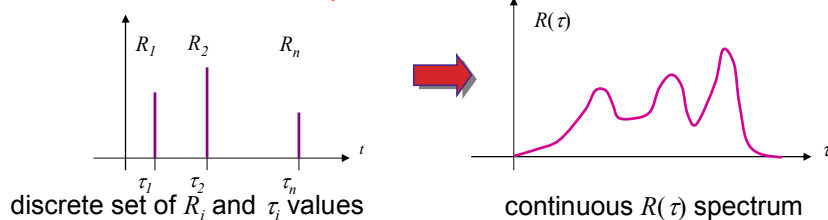
Step-response functions

- for a **distributed** RC system:

$$n \Rightarrow \infty \quad \sum_{i=1}^n \Rightarrow \int_0^{\infty}$$

$$a(t) = \sum_{i=1}^n R_i \cdot [1 - \exp(-t/\tau_i)] \Rightarrow a(t) = \int_0^{\infty} R(\tau) [1 - \exp(-t/\tau)] d\tau$$

characteristic: **$R(\tau)$ time-constant spectrum:**



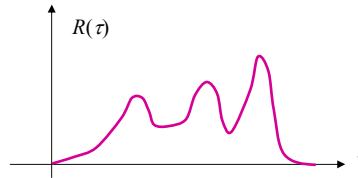
If we know the $R(\tau)$ function, we know the distributed RC system.

4

Time-constant spectrum

Discrete RC stages \Rightarrow discrete set of R_i and τ_i values
Distributed RC system \Rightarrow continuous $R(\tau)$ function

$$a(t) = \int_0^{\infty} R(\tau) [1 - \exp(-t/\tau)] d\tau$$



If we know the $R(\tau)$ function, we know the system.
 $R(\tau)$ is called the **time-constant spectrum**.

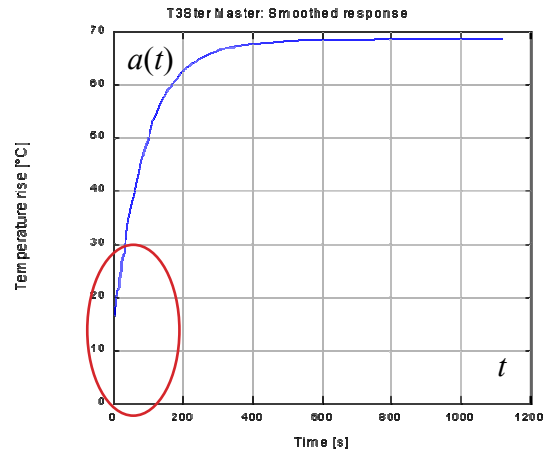
5

Practical problem

- The range of **possible time-constant values** in thermal systems spans over **5..6 decades** of time
 - 100 μ s ..10ms range: semiconductor chip / die attach
 - 10ms ..50ms range: package structures beneath the chip
 - 50ms ..1 s range: further structures of the package
 - 1s ..10s range: package body
 - 10s ..10000s range: cooling assemblies
- Wide time-constant range \Rightarrow data acquisition problem during measurement/simulation: **what is the optimal sampling rate?**

6

Practical problem (cont.)



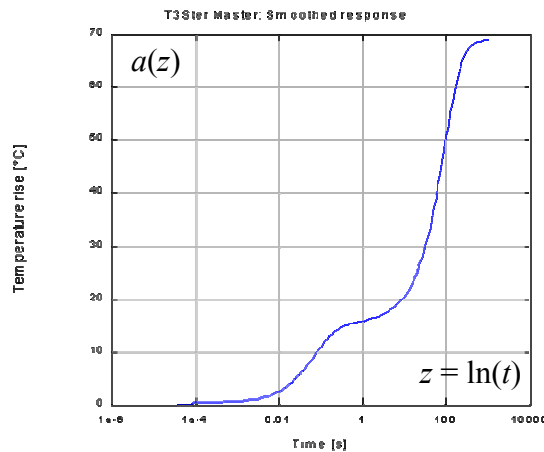
Measured unit-step response of an MCM shown in linear time-scale

Nothing can be seen below the 10s range

Solution: equidistant sampling on *logarithmic time scale*

7

Using logarithmic time-scale



Measured unit-step response of an MCM shown in linear time-scale

Details in all time-constant ranges are seen

Instead of t time we use $z = \ln(t)$ **logarithmic time**

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Step-response in log time

- Switch to logarithmic time scale:

$$a(t) \Rightarrow a(z) \text{ where } z = \ln(t)$$

$a(z)$ is called*

- heating curve or
- thermal impedance curve

- Zth curve

*Sometimes $P \cdot a(z)$ is called heating curve in the literature.

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Step-response in log time

- Zth curve

- Use the chain rule ! $\frac{dy}{dz} = \frac{dy}{dt} \cdot \frac{dt}{dz}$

- Using the $z = \ln(t)$ transformation it can be proven that

$$\frac{d}{dz} a(z) = \int_0^{\infty} R(\zeta) [\exp(z - \zeta) - \exp(z - \zeta)] d\zeta$$

*Sometimes $P \cdot a(z)$ is called heating curve in the literature.

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Step-response in log time

- Note, that $da(z)/dz$ is in a form of a convolution integral:
$$\frac{d}{dz} a(z) = \int_0^{\infty} R(\zeta) [\exp(z - \zeta) - \exp(z - \zeta)] d\zeta$$

Introducing the $w_z(z) = \exp(z - \exp(z))$ function:

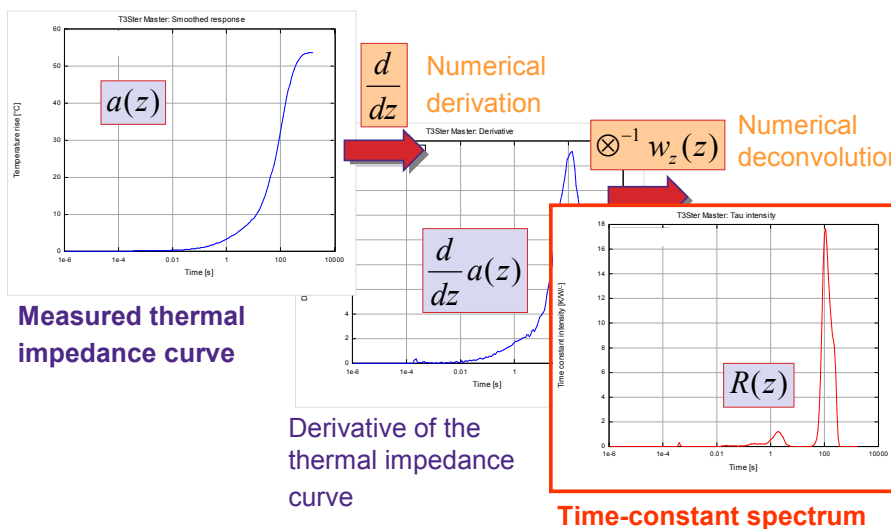
$$\frac{d}{dz} a(z) = \int_0^{\infty} R(\zeta) \cdot w_z(z - \zeta) d\zeta$$

$$\frac{d}{dz} a(z) = R(z) \otimes w_z(z)$$

- From $a(z)$ $R(z)$ is obtained as:
$$R(z) = \left[\frac{d}{dz} a(z) \right] \otimes^{-1} w_z(z)$$

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Extract the time-constant spectrum



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Extract the time-constant spectrum

$$a(z)$$

Must be noise free, must have high time resolution (e.g. 200 points/decade)

$$\frac{d}{dz}$$

Numerical derivation should be accurate: high order techniques yield better results.

Danger of noise enhancement \Rightarrow filtering \Rightarrow loss of ultimate resolution in the time-constant spectrum

$$\otimes^{-1} w_z(z)$$

Numerical deconvolution: Bayes-iteration (for driving point impedance only), frequency-domain inverse filtering (both for driving point and transfer impedances)

$$R(z)$$

False values with small magnitude can be present due to noise enhancement in the procedure. **Negative values represent a transfer impedance.**

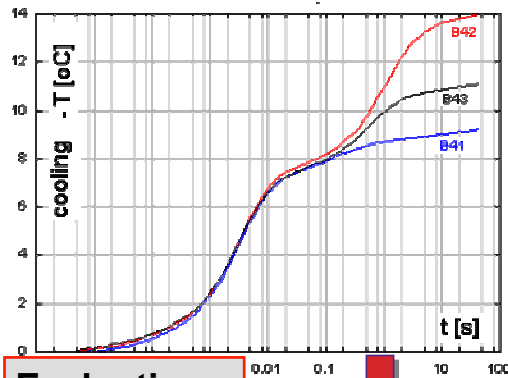
13

Using time-constant spectra

- The time-constant spectrum gives hint for the time-domain behavior of the system for experts
- Time-constant spectra can be further processed and turned into **other characteristic functions**
- These functions are called **structure functions**

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Models of thermal impedances



heating or cooling curves

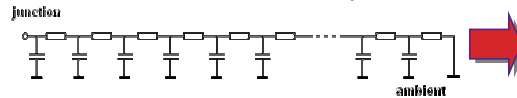


Normalized to 1W dissipation: **thermal impedance curve**

Evaluation:



Network model of a thermal impedance:

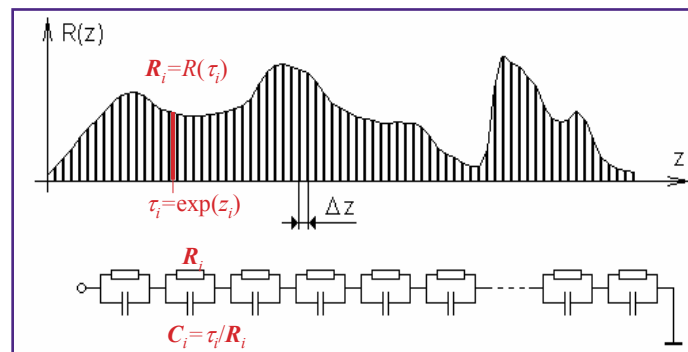


Interpretation of the impedance model:
STRUCTURE FUNCTIONS

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Structure functions 1

- Discretization of $R(z) \Rightarrow$ RC network model in **Foster canonic form** (instead of ∞ spectrum lines, 100..200 RC stages)

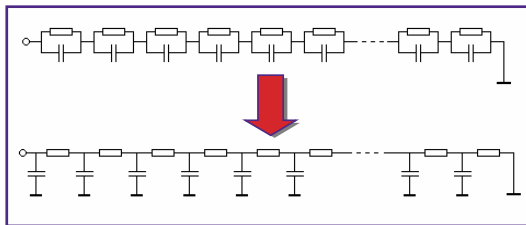


- A discrete RC network model is extracted \Rightarrow name of the method: **NID - network identification by deconvolution**

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Structure functions 2

- The Foster model network is just a theoretical one, does not correspond to the physical structure of the thermal system:
thermal capacitance exists towards the ambient (thermal “ground”) only
- The model network has to be converted into the **Cauer canonic form**:



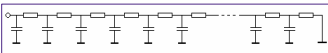
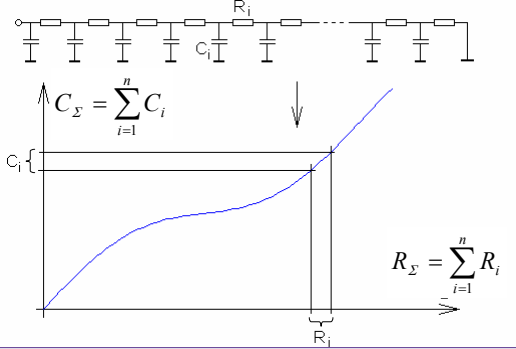
17

- Ronald Martin Foster
- 1896 - 1998
- Wilhelm Cauer
- 1900 - 1945



18

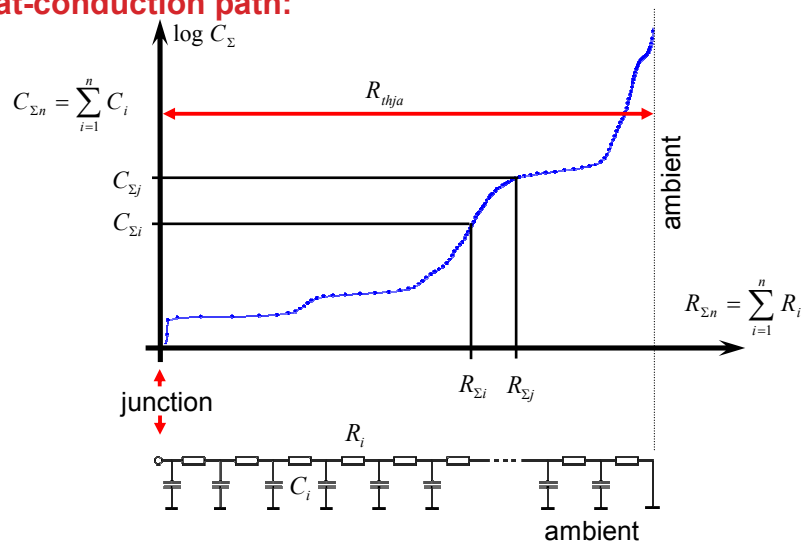
Structure functions 3

- The identified RC model network in the Cauer canonic form now **corresponds to the physical structure**, but
 
- it is very hard to interpret its "meaning"
- Its graphical representation helps:
 
- This is called **cumulative structure function**

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Structure functions 4

The *cumulative structure function* is the *map of the heat-conduction path*:



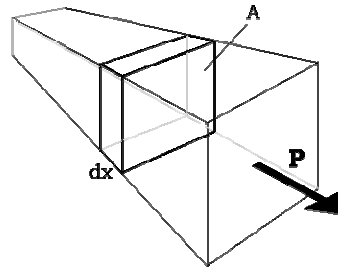
20

Differential structure functions

- The *differential structure function* is defined as the derivative of the cumulative thermal capacitance with respect to the cumulative thermal resistance

$$K(R_{\Sigma}) = \frac{dC_{\Sigma}}{dR_{\Sigma}}$$

$$K(R_{\Sigma}) = \frac{cAdx}{dx/\lambda A} = c\lambda A^2$$



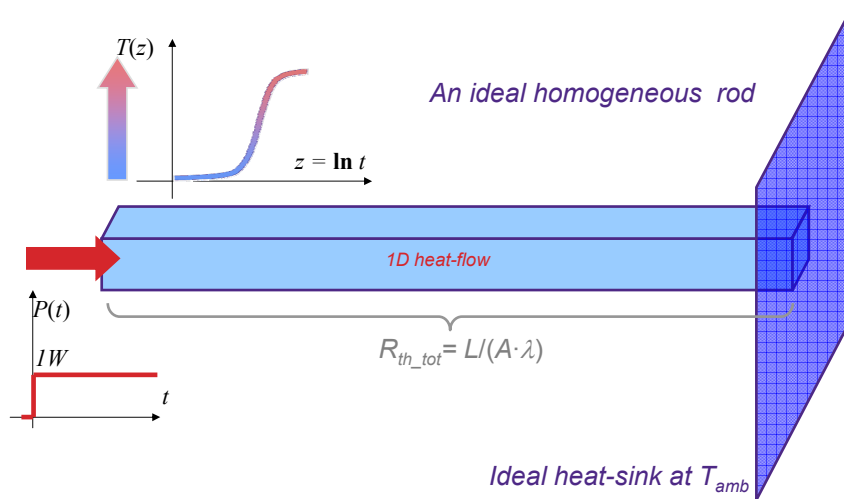
- K is proportional to the square of the cross sectional area of the heat flow path.

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What do structure functions tell us and how?

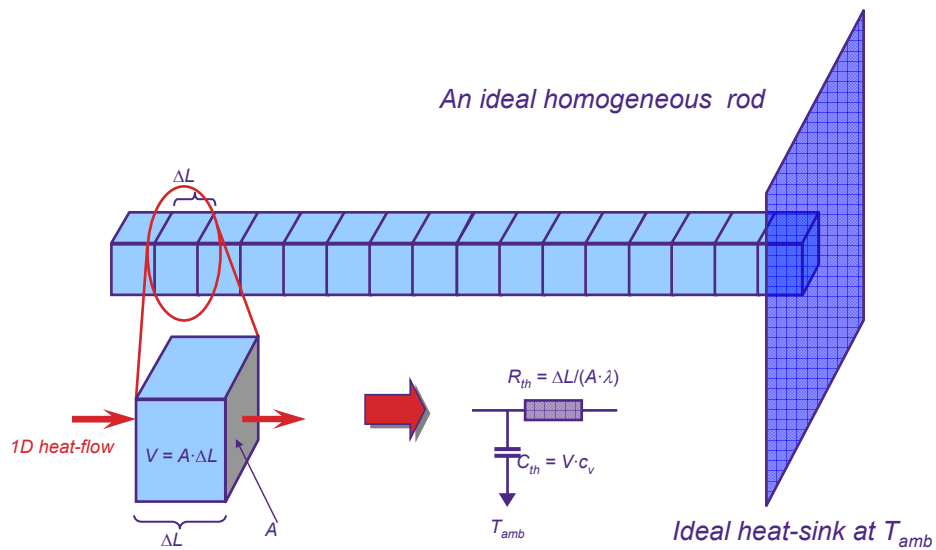
22

A hypothetic example 1



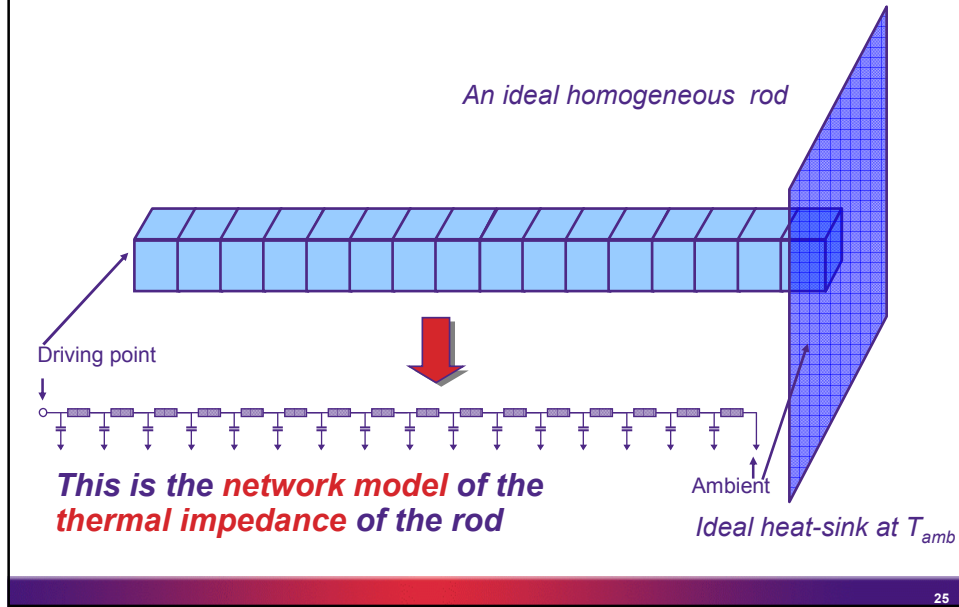
23

A hypothetic example 2



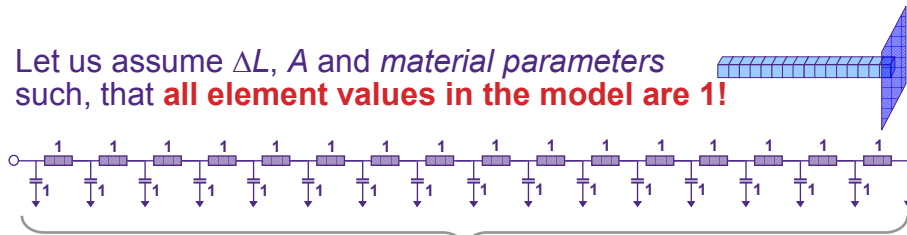
24

A hypothetical example 3



A hypothetical example 4

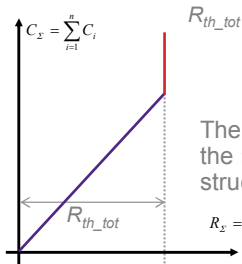
Let us assume ΔL , A and material parameters such, that **all element values in the model are 1!**



It is very easy to create the **cumulative structure function**:

$y=x$ - a straight line

There must be a singularity when we reach the ideal heat-sink.

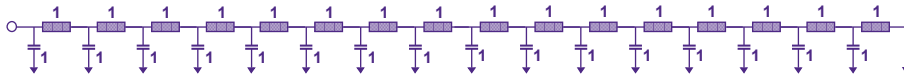
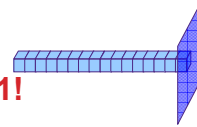


The location of the singularity gives the **total thermal resistance** of the structure.

$$R_x = \sum_{i=1}^n R_i$$

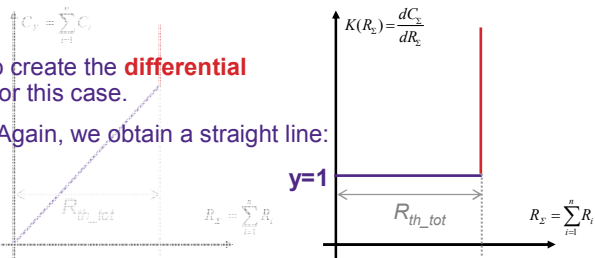
A hypothetical example 5

Let us assume ΔL , A and *material parameters* such, that **all element values in the model are 1!**



It is also very easy to create the **differential structure function** for this case.

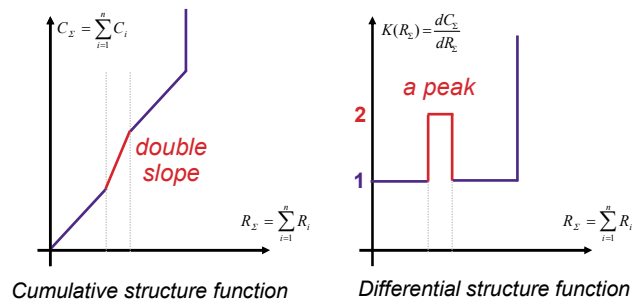
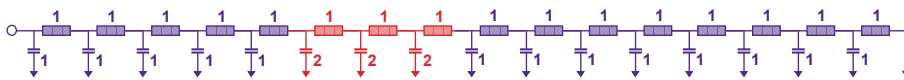
Again, we obtain a straight line:



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A hypothetical example 6

What happens, if e.g. in a certain section of the structure model all capacitance values are equal to 2?



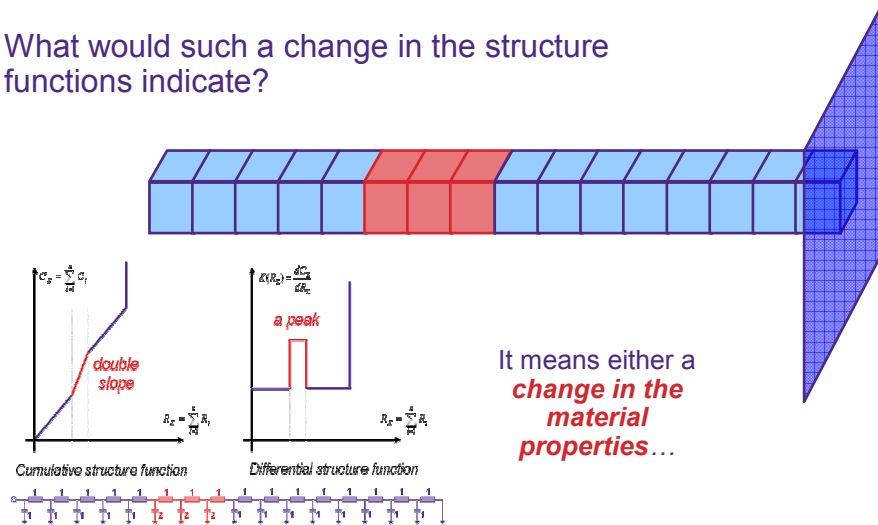
Cumulative structure function

Differential structure function

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A hypothetic example 7

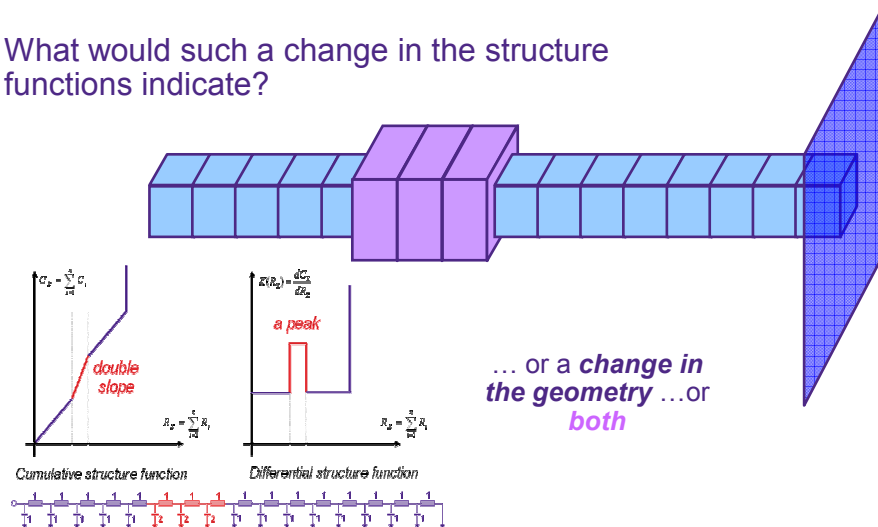
What would such a change in the structure functions indicate?



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A hypothetic example 8

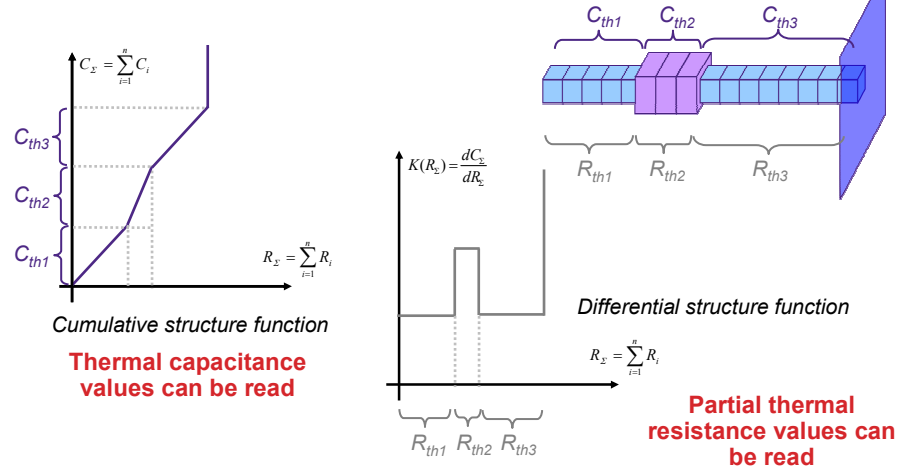
What would such a change in the structure functions indicate?



30

A hypothetic example 9

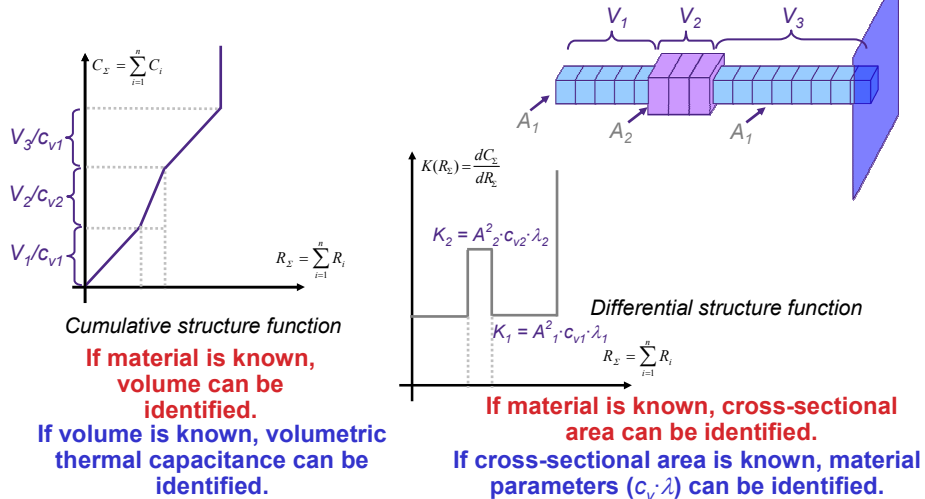
What values can we read from the structure functions?



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A hypothetic example 10

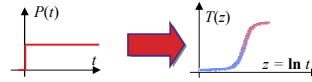
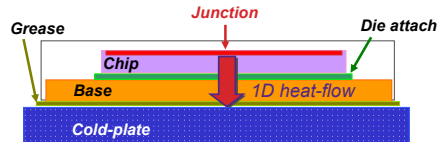
What values can we read from the structure functions?



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Model of 1D flow: structure func.

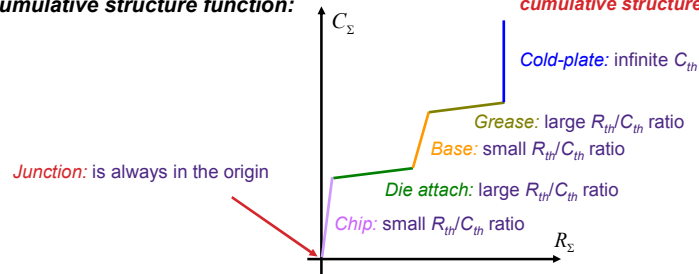
- *Structure functions*: thermal capacitance vs. thermal resistance maps of the heat-flow path



We measure the **thermal transient at the junction**...

...and we convert it into the **cumulative structure function**:

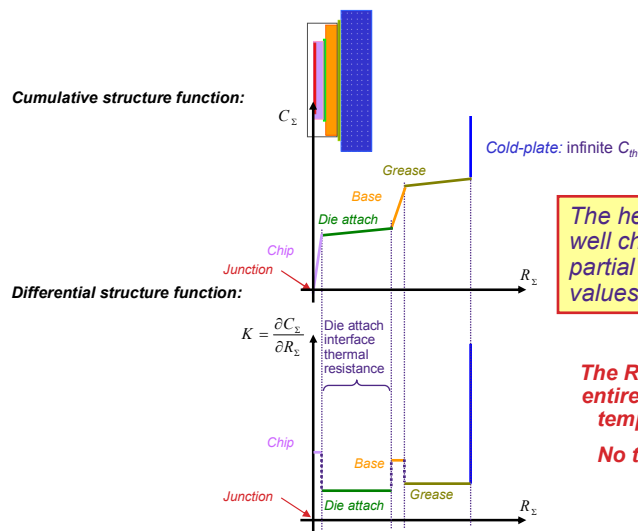
Cumulative structure function:



33

Model of 1D flow: structure func.

- *Structure functions*: maps of the heat-flow path



The heat-flow path can be well characterized e.g. by partial thermal resistance values

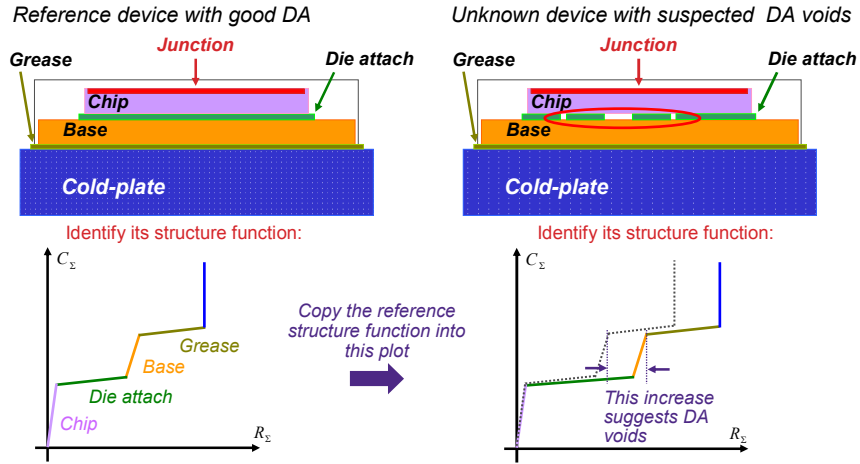
The R_{thDA} value is derived entirely from the junction temperature transient.

No thermocouples are needed.

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DA testing with structure functions

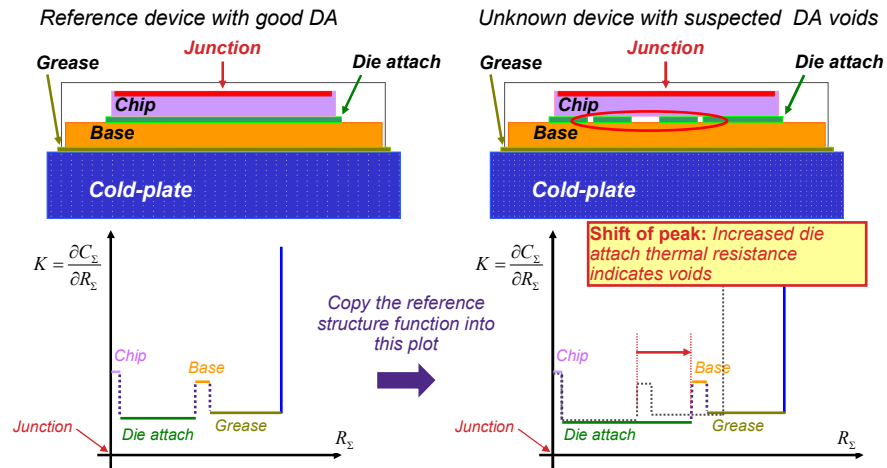
- *Structure functions*: tools for structural analysis and comparison



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DA testing with structure functions

- *Structure functions*: tools for structural analysis and comparison



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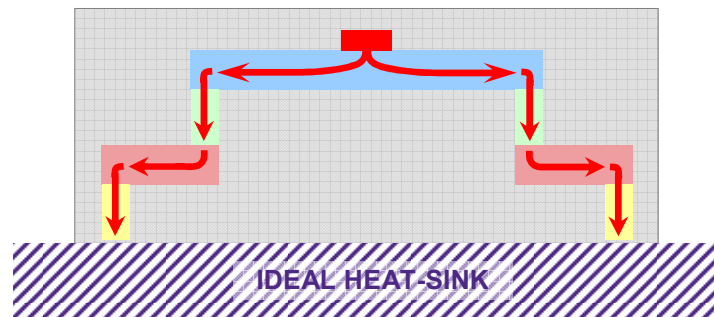
Some conclusions

- Structure functions are **direct models of one-dimensional heat-flow**
 - longitudinal flow (like in case of a rod)
- Also, structure functions are direct models of "essentially" 1D heat-flow, such as
 - radial spreading in a disc (1D flow in polar coordinate system)
 - spherical spreading
 - conical spreading
 - etc.
- Structure functions are "reverse engineering tools": geometry/material parameters can be identified with them

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Some conclusions (cont.)

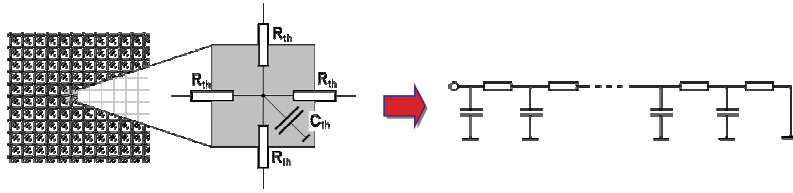
- In many cases a complex heat-flow path can be partitioned into essentially 1D heat-flow path sections connected in series:



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Some conclusions (cont.)

- In case of complex, 3D streaming the derived model has to be considered as an *equivalent physical structure* providing the same thermal impedance as the original structure.



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Some special properties

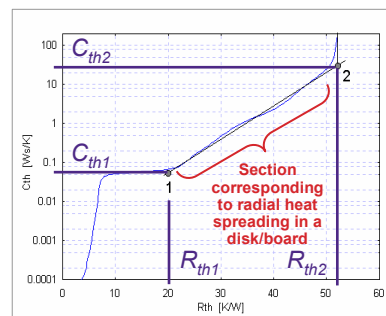
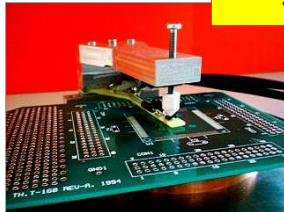
- For "ideal" cases structure functions can be given even by analytical formulae

– for a rod:

$$C_{\Sigma} = \text{const} \cdot R_{\Sigma}$$

– for radial spreading in a disc of w thickness and λ thermal conductivity:

$$\lambda w = \frac{1}{4\pi} \frac{\ln(C_{th2} / C_{th1})}{R_{th2} - R_{th1}}$$



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